

# Introduction to Finite Automata

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# Table of Contents

- 1 Finite Automata
- 2 New From Old
- 3 Non-Deterministic vs. Deterministic
- 4 New From Old (again)
- 5 Next Class

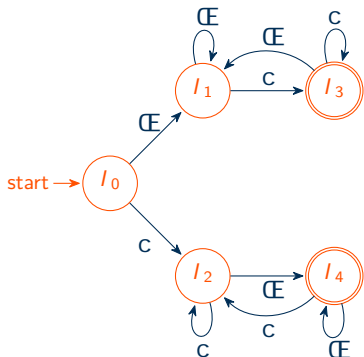


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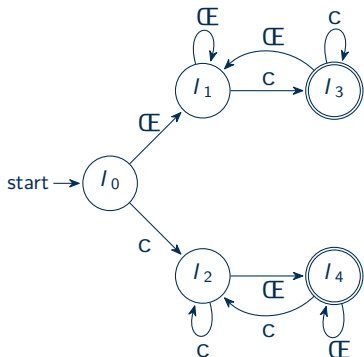
# State Diagram and Finite Automaton



- States:  $k = \{l_0; l_1; l_2; l_3; l_4\}$



# State Diagram and Finite Automaton

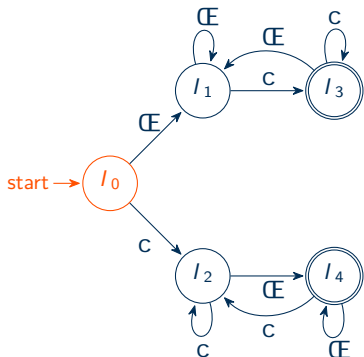


• States:  $k = \{l_0; l_1; l_2; l_3; l_4\}$

• Alphabet:  $\Sigma = \{f; g\}$



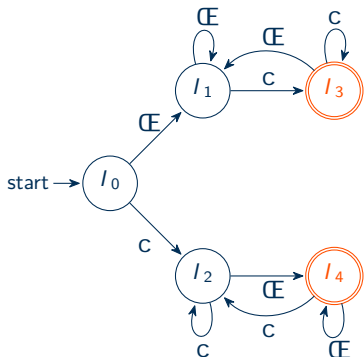
# State Diagram and Finite Automaton



- States:  $k = \{l_0; l_1; l_2; l_3; l_4\}$
- Alphabet:  $\Sigma = \{a; b\}$
- Start State:  $l_0$



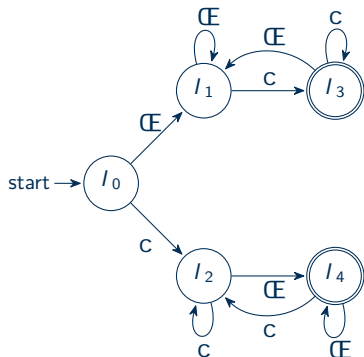
# State Diagram and Finite Automaton



- States:  $k = \{l_0; l_1; l_2; l_3; l_4\}$
- Alphabet:  $\Sigma = \{c; \epsilon\}$
- Start State:  $l_0$
- Accept States:  $G = \{l_3; l_4\}$



# State Diagram and Finite Automaton

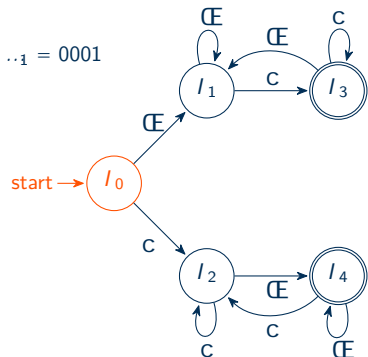


- States:  $K = \{l_0; l_1; l_2; l_3; l_4\}$
- Alphabet:  $\Sigma = \{0; 1\}$
- Start State:  $l_0$
- Accept States:  $G = \{l_3; l_4\}$
- Language:  $X = \{1^* 0; 0^* 1\}$





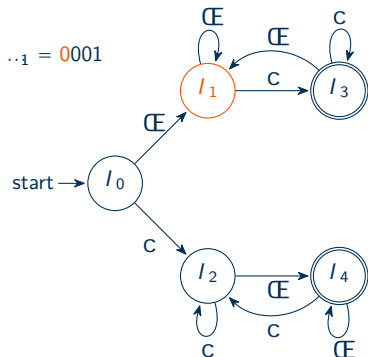
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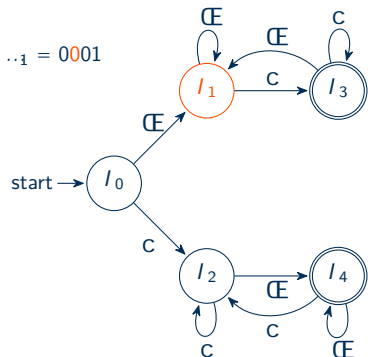
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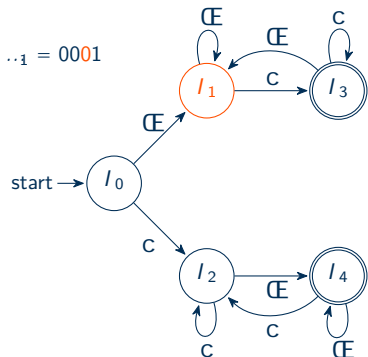
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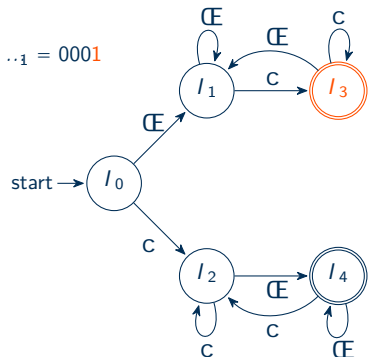
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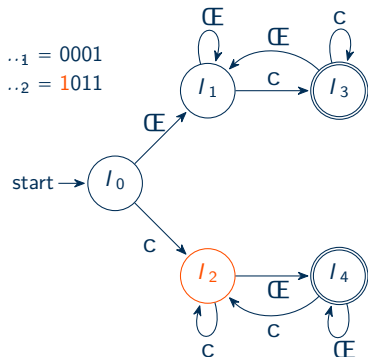
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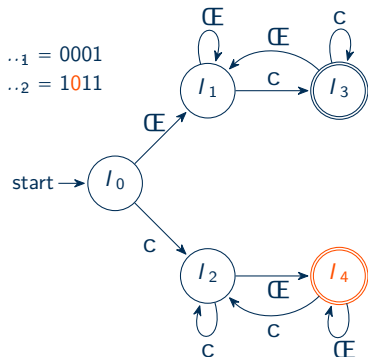
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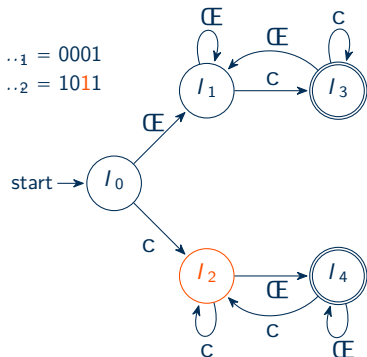
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- States:  $K = \{l_0; l_1; l_2; l_3; l_4\}$
- Alphabet:  $\Sigma = \{0; 1\}$
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- Accept States:  $G = \{l_3; l_4\}$
- Language:  $X = \{10; 01\}$



# State Diagram and Finite Automaton

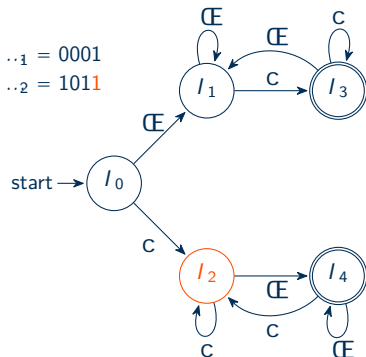


- States:  $k = \{l_0; l_1; l_2; l_3; l_4\}$
- Alphabet:  $\Sigma = \{0; 1\}$
- Start State:  $l_0$
- Accept States:  $G = \{l_3; l_4\}$
- Language:  $X = \{1^* 0; 0^* 1\}$





# State Diagram and Finite Automaton



- States:  $K = \{I_0; I_1; I_2; I_3; I_4\}$
- Alphabet:  $\Sigma = \{0; 1\}$
- Start State:  $I_0$
- Accept States:  $G = \{I_3; I_4\}$
- Language:  $X = \{1^k 0; 0^k 1\}$



# Formal Definition

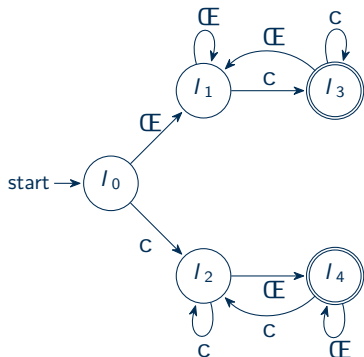
## Definition (Finite Automaton)

A finite automaton is a 5-tuple  $(K; \Sigma; \delta; I_0; G)$ , where

- 1  $K$  is a finite set of states,
- 2  $\Sigma$  is a finite alphabet,
- 3  $\delta: K \times \Sigma \rightarrow K$  is the transition function,
- 4  $I_0 \subseteq K$  is the set of initial states, and
- 5  $G \subseteq K$  is the set of accepting states.



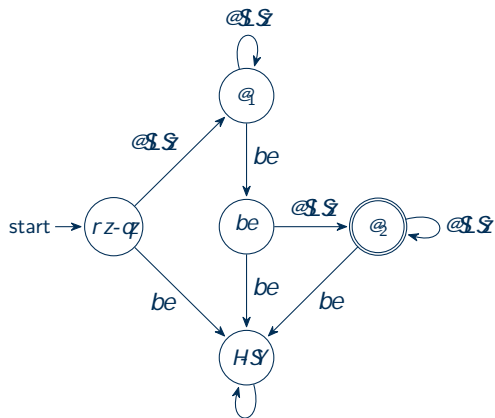
# Transition Function



	0	1
$l_0$	$l_1$	$l_2$
$l_1$	$l_1$	$l_3$
$l_2$	$l_4$	$l_2$
$l_3$	$l_1$	$l_3$
$l_4$	$l_4$	$l_2$



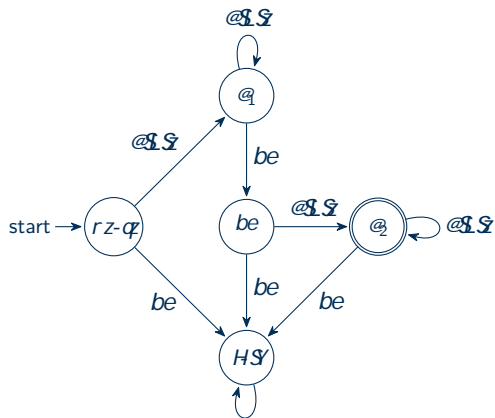
## Another Example



- $k = frz-\varphi; @; @; be; HSg$
- $= be [ @S$ 
  - $be = f+; ; g$
  - $@S = f0;1;2;:::;9g$
- $G = f@g$
- $XE m$



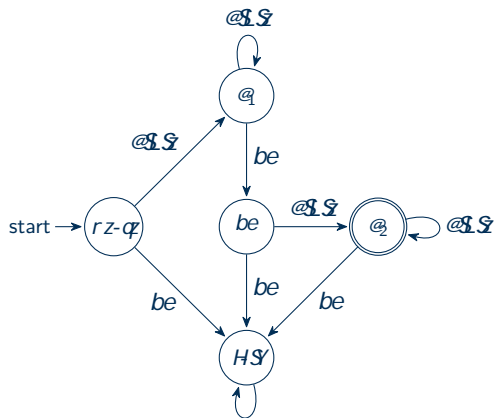
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- $\dots = |I + \{v|$



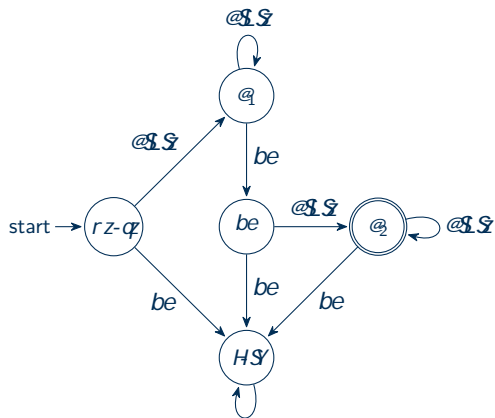
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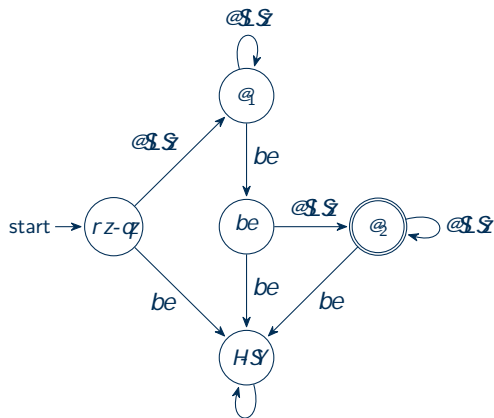
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- $\dots = |vl \quad Jlv \quad cD$



## Another Example

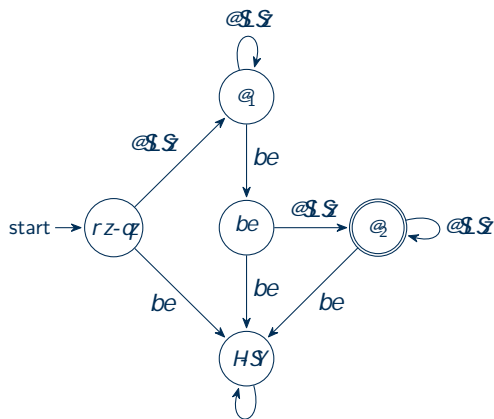


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- $= be [ @S$ 
  - $be = f+; ; g$
  - $@S = f0;1;2;:::;9g$
- $G = f@g$
- $XE; b \setminus 4S^Cz.b S^zL C\varphi s$
- $\dots = |I + \{v|$
- $\dots = \{I \quad vu$
- $\dots = |v| \quad JI v \quad cD$





## Another Example



- $k = frz-\varphi; @_1; @_2; be; HSg$
- $= be [ @1S$ 
  - $be = f+; ; g$
  - $@1S = f0;1;2;:::;9g$
- $G = f@_2g$
- $XE; b \setminus 4S^Cz.b S^zL C\phi s$
- $\dots = |I + \{v|$
- $\dots = \{I \quad vu$
- $\dots = |v| \quad |I v \quad cD$

The language  $X$  is called a  $q\mathcal{L}\sim YqY^{\wedge}L\sim LC$  because it is recognized by a finite automaton.



# Satisfying a Description

## Problem

$\{ \text{b}^n \text{szq} \mid z \in \{ \text{c}, \text{e}, \text{s} \}^* \text{ and } n \geq 1 \}$



# Satisfying a Description

## Problem

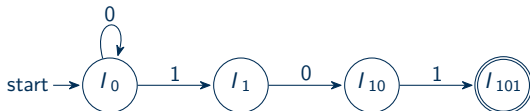
; b^szq-z - " ^Sc - ~zb\ - zb^ zP-z - <<Cezs b^%o.bq@s S^ = fCEcg C^@S^L S^ cCEi



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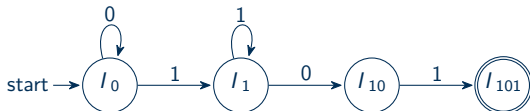
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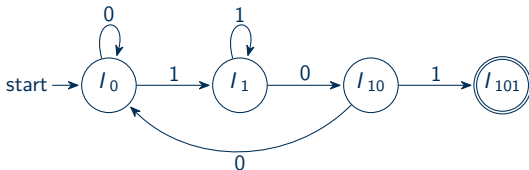
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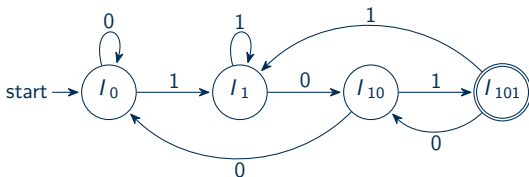
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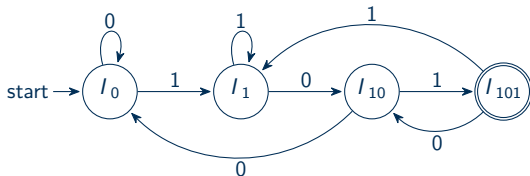
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# Satisfying a Description

## Problem

; b^szq-z - " ^SC--zb\ -zb^ zP-z - <<Cezs b^%o.bq@s S^ = fCEcg C^@S^L S^ cCEi



Check what happens to 101 independent of where we start.

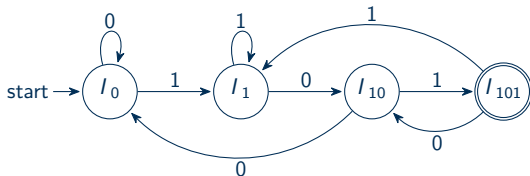




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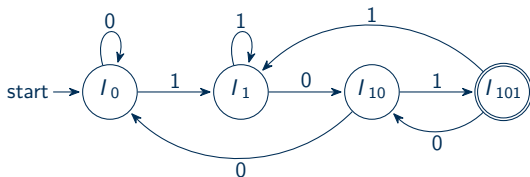
Check what happens to 010 independent of where we start.



# Satisfying a Description

## Problem

; b^szq-<z - " ^sC - ~zb\ - zb^ zP-z - <<Cezs b^%o. bq@s S` = fCEcg C^@SL S` cCEi



Note that this means we don't need to "remember" the whole string to check its ending.



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# Creating New Automata

## Definition

Let  $L_1$  and  $L_2$  be regular languages. We define the regular operations  $L_1 \cup L_2$ ,  $L_1 \cap L_2$ , and  $L_1 \cdot L_2$  as follows:

- $L_1 \cup L_2$ :  $L_1 \cup L_2 = \{x \mid x \in L_1 \vee x \in L_2\}$
- $L_1 \cap L_2$ :  $L_1 \cap L_2 = \{x \mid x \in L_1 \wedge x \in L_2\}$
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- $L_1 - L_2 = \{x \mid x \in L_1 \wedge x \notin L_2\}$
- $L_1 \oplus L_2 = (L_1 \cup L_2) - (L_1 \cap L_2)$



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- $L_1 \cup L_2 = L_1 \cup L_2$
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- $L_1 \cup L_2 = f0;1g$

- $L_1 \cap L_2 = f-;4g$

- $L_1 \setminus L_2 = f0;1;-;4g$





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- $L_1 \cup L_2 = (L_1 \cap L_2) \cup (L_1 \setminus L_2) \cup (L_2 \setminus L_1)$



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- $L_1 \setminus L_2 = \{ x \mid x \in L_1 \wedge x \notin L_2 \}$



# Details on Union

Given two finite automata

$$A_1 = (K_1, \Sigma, \delta_1, l_1, G_1) \quad \text{and} \quad A_2 = (K_2, \Sigma, \delta_2, l_2, G_2)$$

their union is constructed as follows:

- $K = K_1 \cup K_2$



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- $\delta = \delta_1 \cup \delta_2$



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their union is constructed as follows:

- $K = K_1 \cup K_2$
- $\delta = \delta_1 \cup \delta_2$
- $\delta(q; \sigma) = \delta_1(q; \sigma) \cup \delta_2(q; \sigma)$



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Given two finite automata

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their union is constructed as follows:

- $K = K_1 \cup K_2$
- $\delta = \delta_1 \cup \delta_2$
- $\delta(q; a) \in K \setminus K_1 \setminus K_2 : ((q; a); -) = (q_1(q; -); q_2(a; -))$
- $I_0 = (I_1; I_2)$



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- $\Sigma = \Sigma_1 \cup \Sigma_2$
- $\delta(q; a) = \delta_i(q; a) \quad \text{if } (q; a) \in \delta_i \text{ for } i \in \{1, 2\}$
- $I_0 = (I_1 \cup I_2)$
- $G = \{q \mid q \in G_1 \text{ or } q \in G_2\}$



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$$A_1 = (K_1; \Sigma; \delta_1; I_1; G_1) \quad A_2 = (K_2; \Sigma; \delta_2; I_2; G_2)$$

their union is constructed as follows:

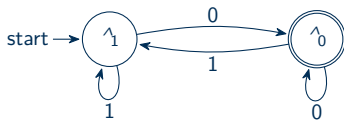
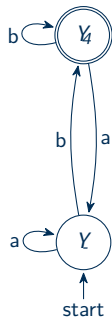
- $K = K_1 \cup K_2$
- $\Sigma = \Sigma_1 \cup \Sigma_2$
- $\delta(q; a) = \delta_i(q; a) \text{ if } q \in K_i \text{ and } a \in \Sigma_i$
- $I_0 = (I_1 \cup I_2)$
- $G = \{q \mid q \in G_1 \text{ or } q \in G_2\}$

f] bzc q 2 G1 - ^@q 2 G2 ..b~Y@ 4C S'z CpC zS ^g

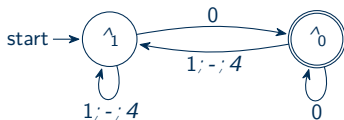
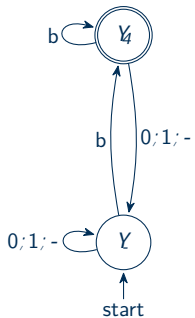




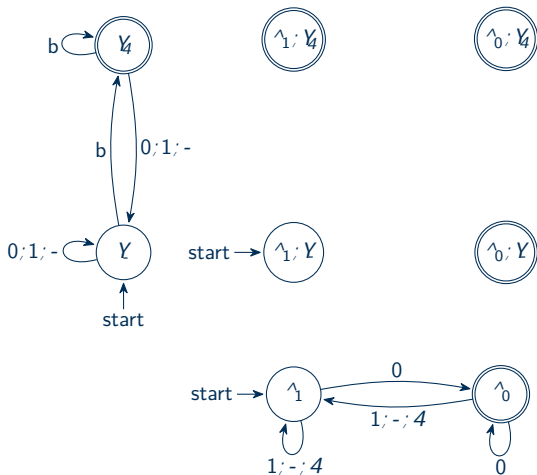
# Union Example



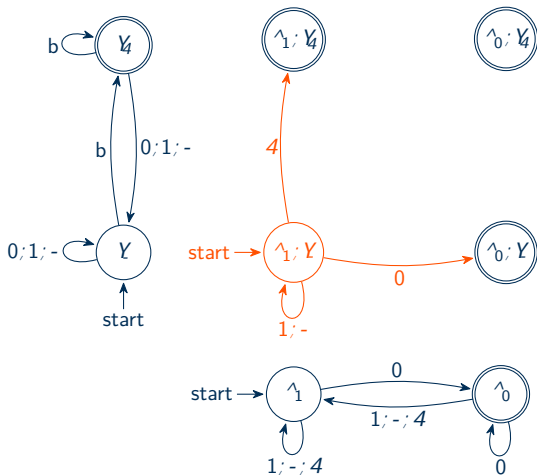
# Union Example



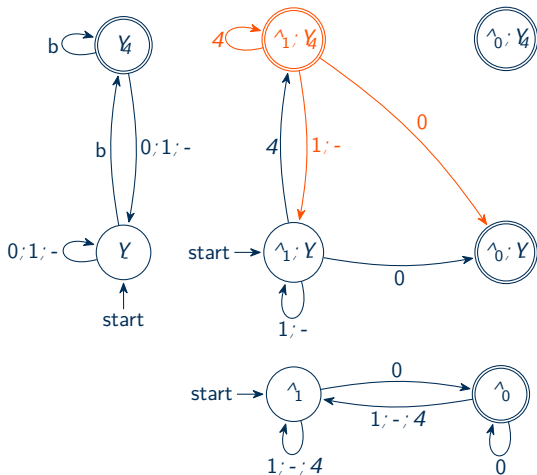
# Union Example



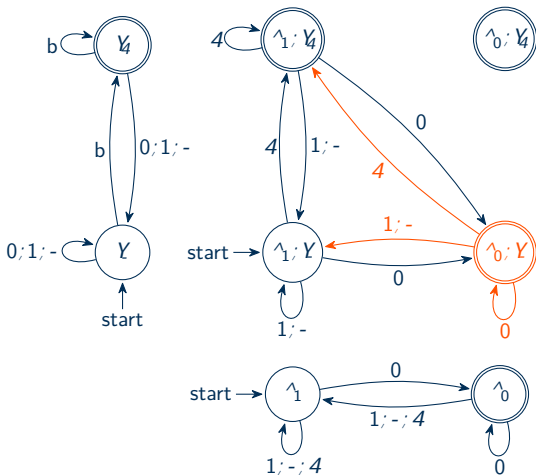
# Union Example



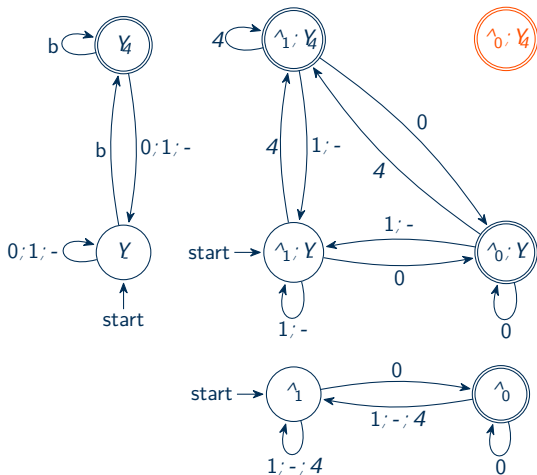
# Union Example



# Union Example



# Union Example



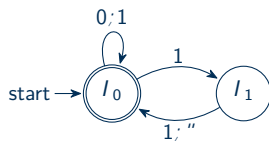
# Table of Contents

- 1 Finite Automata
- 2 New From Old
- 3 Non-Deterministic vs. Deterministic**
- 4 New From Old (again)
- 5 Next Class





# Non-Deterministic Automata

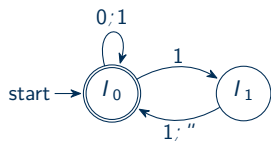


	0	1	"
$l_0$	$fl_{0g}$	$fl_0; l_{1g}$	$;$
$l_1$	$;$	$fl_{0g}$	$fl_{0g}$

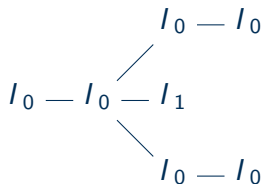
... = 010



# Non-Deterministic Automata



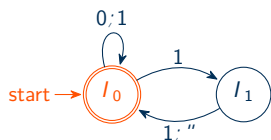
	0	1	"
$l_0$	$fl_{0g}$	$fl_0; l_{1g}$	$;$
$l_1$	$;$	$fl_{0g}$	$fl_{0g}$



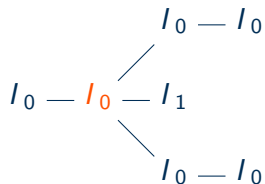
... = 010



## Non-Deterministic Automata



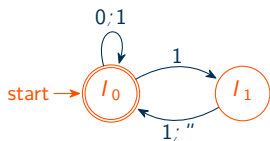
	0	1	"
$l_0$	<i>fl<sub>0g</sub></i>	<i>fl<sub>0</sub>;l<sub>1g</sub></i>	<i>;</i>
$l_1$	<i>;</i>	<i>fl<sub>0g</sub></i>	<i>fl<sub>0g</sub></i>



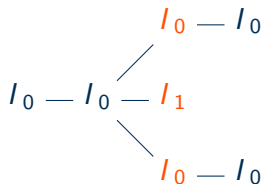
... = 010



# Non-Deterministic Automata



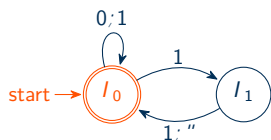
	0	1	"
$l_0$	$fl_{0g}$	$fl_{0; l_1g}$	$;$
$l_1$	$;$	$fl_{0g}$	$fl_{0g}$



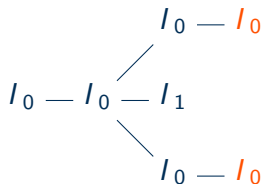
... = 010



# Non-Deterministic Automata



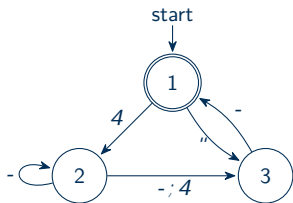
	0	1	"
$l_0$	$fl_{0g}$	$fl_{0; l_1g}$	$;$
$l_1$	$;$	$fl_{0g}$	$fl_{0g}$



... = 010



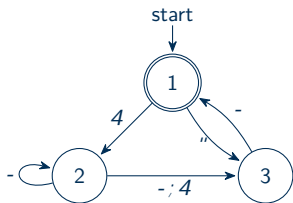
## Equivalence to Deterministic (Slide 1)



	-	4	"
1	/	{2}	{3}
2	{2,3}	{3}	/
3	{1}	/	/



## Equivalence to Deterministic (Slide 1)

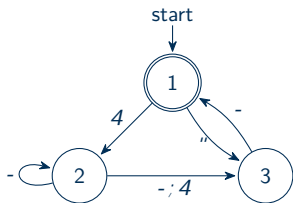


	-	4	"
1	;	{2}	{3}
2	{2,3}	{3}	;
3	{1}	;	;

- $k = f1;2;3g$
- $" = f-;4;"g$
- $rz-\varnothing = f1g$
- $G = f1g$



## Equivalence to Deterministic (Slide 1)



	-	4	"
1	;	{2}	{3}
2	{2,3}	{3}	;
3	{1}	;	;

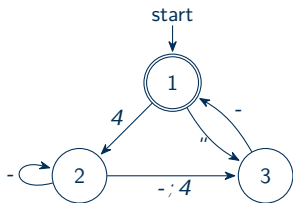
- $k^0 = P(k)$  (Power set of  $k$ )

- $k = f1;2;3g$
- $" = f-;4;"g$
- $rz-\varnothing = f1g$
- $G = f1g$





## Equivalence to Deterministic (Slide 1)



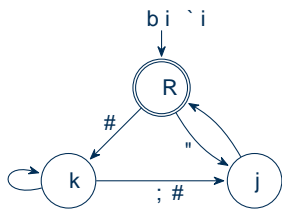
	-	4	"
1	;	{2}	{3}
2	{2,3}	{3}	;
3	{1}	;	;

- $k^{\emptyset} = P(k)$  (Power set of  $k$ )
- $\emptyset = f-;4g$

- $k = f1;2;3g$
- $" = f-;4;"g$
- $rz-\varnothing = f1g$
- $G = f1g$



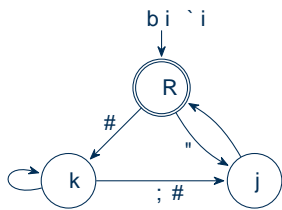
## 1 [mBp H2M+2 iQ .2i2`KBMBbiB+ UaI


 $Z = f R k j g$ 
 $" = f ; # " g$ 
 $a i `i f R$ 
 $6 = f R$ 

		#	"
R	;	&k'	&j'
k	&k-j'	&j'	;
j	&R'	;	;

 $Z^0 = P ( Z ) U S Q r 2 ` b Z V Q 7$ 
 $^0 = f ; # g$ 
 $1(f R) = f R j g$

## 1 [mBp H2M+2 iQ .2i2`KBMBbiB+ UaI



$Z = f R k j g$   
 $" = f ; \# " g$   
 $a i \text{ `} \# f R j g$   
 $6 = f R j g$

		#	"
R	;	&k'	&j'
k	&k-j'	&j'	;
j	&R'	;	;

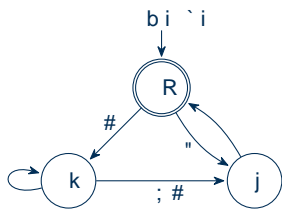
$Z^0 = P ( Z ) U S Q r 2 \text{ ` } b Z V Q 7$

$^0 = f ; \# g$

$1(f R) = f R j g$

$a i \text{ `} \# f R j g$

## 1 [mBp H2M+2 iQ .2i2`KBMBbiB+ UaI



$Z = f R k j g$   
 $" = f ; \# " g$   
 $a i \text{ `} \# f R j g$   
 $6 = f R j g$

		#	"
R	;	&k'	&j'
k	&k-j'	&j'	;
j	&R'	;	;

$Z^0 = P ( Z ) U S Q r 2 \text{ ` } b Z V Q 7$

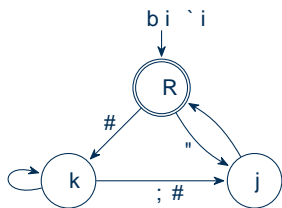
$^0 = f ; \# g$

$1(f R) = f R j g$

$a i \text{ `} \# f R j g$

$6^0 = f f R j g ; f R k g ; f R j g ; f R k j g g$

## 1 [m Bp H2M+2 iQ .2i2`KBMBbiB+ UaI



$Z = f R k j g$   
 $" = f ; \# " g$   
 $a i \text{ `} \neq f R j g$   
 $6 = f R j g$

		#	"
R	;	&k'	&j'
k	&k-j'	&j'	;
j	&R'	;	;

$Z^0 = P(Z) USQR2` bZV Q7$

$^0 = f ; \# g$

$1(f R) = f R j g$

$a i \text{ `} \neq f R j g$

$6^0 = ff R j g; f R k g; f R j g; f R k j g g$

$^0 = ?$

## 1 [m Bp H2M+2 iQ .2i2`KBMBbiB+ Ua

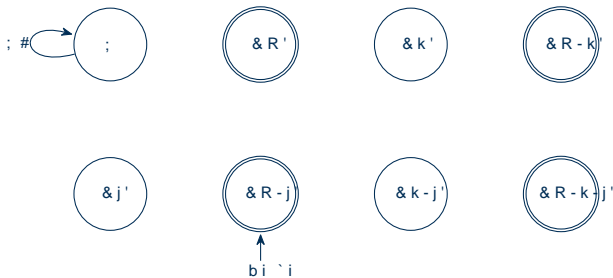
		#	"
R	;	&k'	&j'
k	&k-j'	&j'	;
j	&R'	;	;



↑  
bi`i

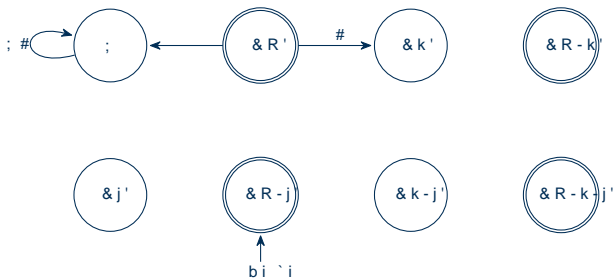
## 1 [m Bp H2M+2 iQ .2i2`KBMBbiB+ Ua

		#	"
R	;	&k'	&j'
k	&k-j'	&j'	;
j	&R'	;	;



## 1 [m Bp H2M+2 iQ .2i2`KBMBbiB+ Ua

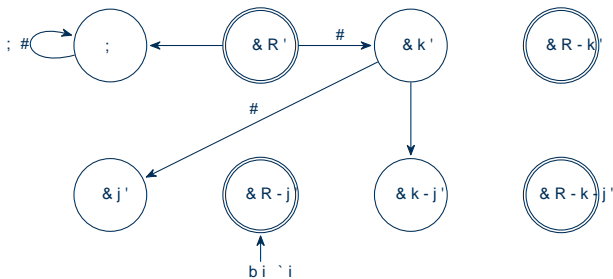
		#	"
R	;	&k'	&j'
k	&k-j'	&j'	;
j	&R'	;	;





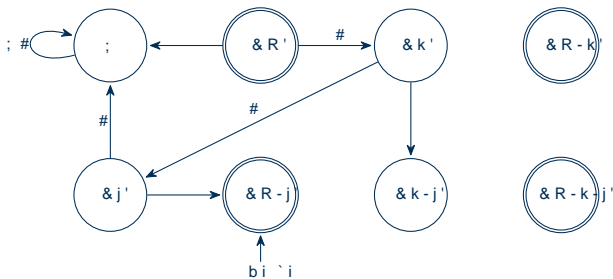
## 1 [m Bp H2M+2 iQ .2i2`KBMBbiB+ Ua

		#	"
R	;	&k'	&j'
k	&k-j'	&j'	;
j	&R'	;	;



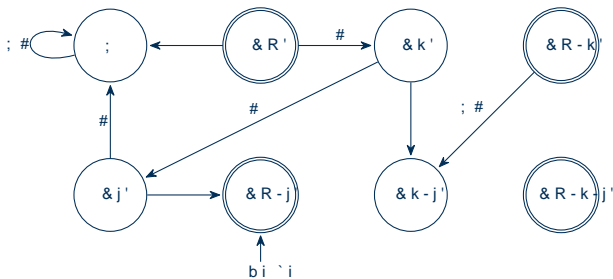
## 1 [m Bp H2M+2 iQ .2i2`KBMBbiB+ Ua

		#	"
R	;	&k'	&j'
k	&k-j'	&j'	;
j	&R'	;	;



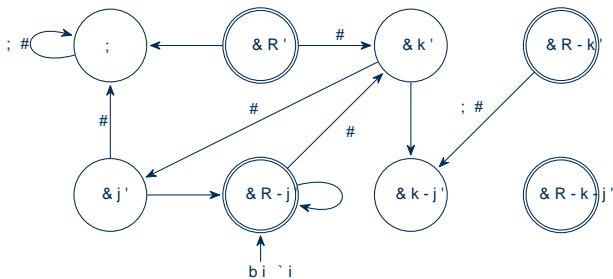
## 1 [m Bp H2M+2 iQ .2i2`KBMBbiB+ Ua

	#	"
R	&k'	&j'
k	&k-j'	;
j	&R'	;



## 1 [m Bp H2M+2 iQ .2i2`KBMBbiB+ Ua

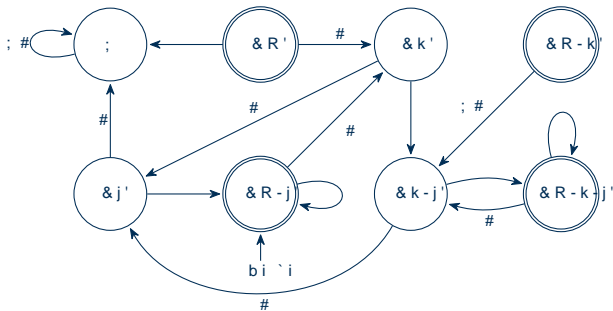
	#	"
R	&k'	&j'
k	&k-j'	;
j	&R'	;





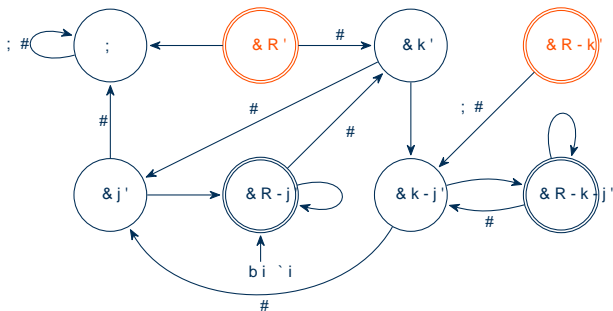
## 1 [m Bp H2M+2 iQ .2i2`KBMBbiB+ Ua

	#	"
R	; &k'	&j'
k	&k-j'	; &j'
j	&R'	; &j'



## 1 [mBp H2M+2 iQ .2i2`KMBBiB+ Ua

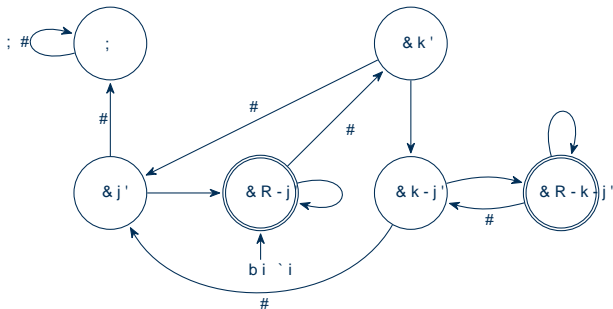
	#	"
R	; &k'	&j'
k	&k-j'	; &j'
j	&R'	; &j'



q2 + M 2HBKBM i2 bi i2b i? i `2 QMHv

## 1 [mBp H2M+2 iQ .2i2`KBMBbiB+ Ua

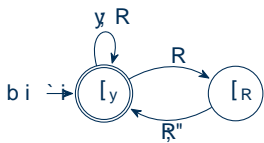
		#	"
R	;	&k'	&j'
k	&k-j'	&j'	;
j	&R'	;	;



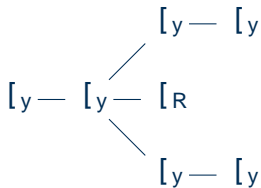
q2 + M 2HBKBM i2 bi i2b i? i `2 QMHv



## LQM@.2i2`KBMBbiB+ miQK i



	$y$	$R$	"
$[y]$	$f [y]g$	$f [y]; [R]$	$;$
$[R]$	$;$	$f [y]g$	$f [y]g$



$$r = yRy$$

h #H2 Q7 \*QM i2Mib

R 6BMBi2 miQK i

k L2r 6`QK PH/

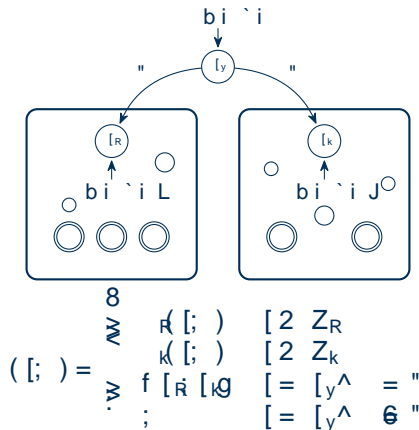
j LQM@.2i2`KBMBbiB+ pbX .2i2`KBMBbiB+

9 L2r 6`QK PH/ U ; BMV

8 L2ti \*H bb

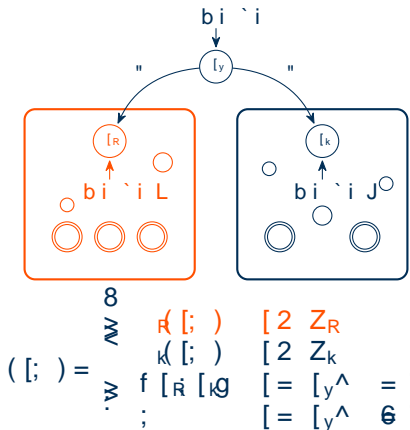
## IMBQM \_2 p β b'Bi2/ ,

bbmK2 i? i i?2 `2; mH BH `M ;m2 b22 Mi2/ #v i?2 }M  
 L M/ i?2 `2; mH ` H BM; m2 T22b2Mi2/ #v i?2 }M Bi2  
 i?2M i?2B+QM #2 `2T`2b2Mi2/ b #2HQrX



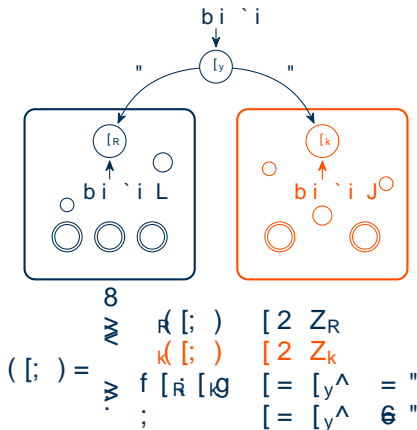
## IMBQM \_2 p β b' Bi2/ ,

bbmK2 i? i i?2 `2; mH BH `M; m2 b22 Mi2/ #v i?2 }M  
 L M/ i?2 `2; mH ` H BM; m2 T22 b2 Mi2/ #v i?2 }M Bi2  
 i?2 M i?2 B+QM #2 `2T`2 b2 Mi2/ b #2 HQRX



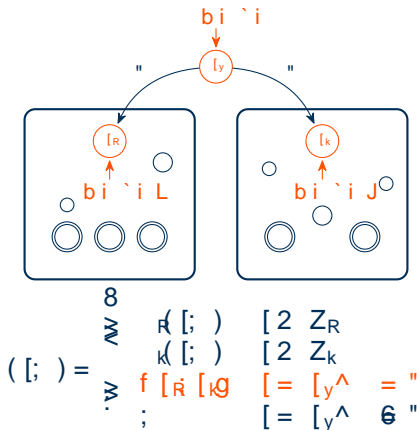
## IMBQM \_2 p β b'Bi2/ ,

bbmK2 i? i i?2 `2; mH BH `M ;m2 b22 Mi2/ #v i?2 }M  
 L M/ i?2 `2; mH ` H BM; m2 T22b2Mi2/ #v i?2 }M Bi2  
 i?2M i?2B+QM #2 `2T`2b2Mi2/ b #2HQrX



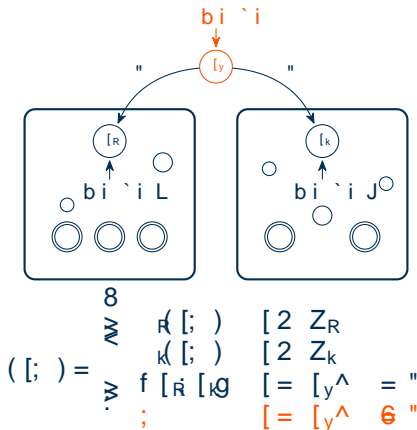
## IMBQM \_2 p β b'Bi2/ ,

bbmK2 i? i i?2 `2; mH BH `M ;m2 b22 Mi2/ #v i?2 }M  
 L M/ i?2 `2; mH ` H BM; m2 T22b2Mi2/ #v i?2 }M Bi2  
 i?2M i?2B+QM #2 `2T`2b2Mi2/ b #2HQRX



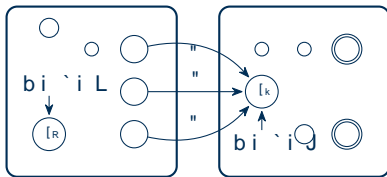
## IMBQM \_2 p β b'Bi2/ ,

bbmK2 i? i i?2 `2; mH BH `M ;m2 b22 Mi2/ #v i?2 }M  
 L M/ i?2 `2; mH ` H BM; m2 T22b2Mi2/ #v i?2 }M Bi2  
 i?2M i?2B+QM #2 `2T`2b2Mi2/ b #2HQrX



\*  $QM + i^2 M i B' Q M,$

bbmK2 i? i i?2 `2; mH BH `M; m2 p22 Mi2/ #v i?2 } M  
 L M/ i?2 `2; mH ` H BMB; m2 T22 b2 Mi2/ #v i?2 } M B i2  
 i?2 M i?2 QBM + i2 M + i B' Q M `2 T`2 b2 Mi2/ b #2 H Q r X

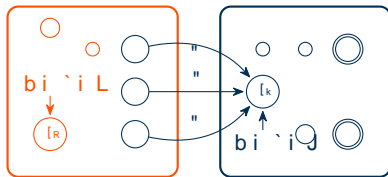


$$\begin{aligned}
 ([; ) = & \begin{matrix} \delta \\ \mathcal{W} \\ \cdot \mathcal{W} \end{matrix} \begin{pmatrix} \mathcal{R}([; ) \\ \mathcal{R}([; ) \\ \mathcal{R}([; ) \\ \mathcal{K}([; ) \end{pmatrix} \begin{matrix} [2 Z_R^\wedge [626_R \\ [2 6_R^\wedge \mathcal{E} " \\ [2 6_R^\wedge = " \\ [2 Z_k \end{matrix}
 \end{aligned}$$



\*  $QM + i2M iB'QM,$

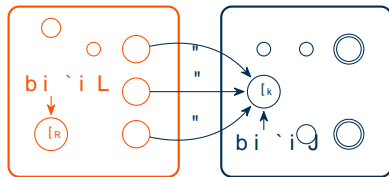
bbmK2 i? i i?2 `2; mH BH `M; m2 p22 Mi2/ #v i?2 } M  
 L M/ i?2 `2; mH ` H BMB; m2 T22 b2 Mi2/ #v i?2 } M Bi2  
 i?2 M i?2 BM + i2 M + i B'QM `2 T`2 b2 Mi2/ b #2 HQRX



$$\begin{pmatrix} l; \end{pmatrix} = \begin{matrix} \cdot W \\ \cdot W \\ \cdot W \\ \cdot W \end{matrix} \begin{pmatrix} R(l; ) \\ R(l; ) \\ R(l; ) \\ R(l; ) \end{pmatrix} [f \quad l_k] \begin{matrix} [2 \quad Z_R^A \\ [2 \quad 6_R^A \\ [2 \quad 6_R^A \\ [2 \quad Z_k \end{matrix} \begin{matrix} [626_R \\ \Theta \\ = \\ \end{matrix}$$

\*  $QM + i2M iB'QM,$

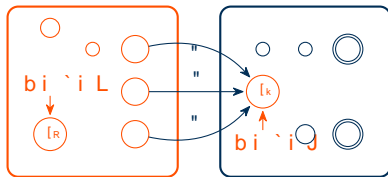
bbmK2 i? i i?2 `2; mH BH `M; m2 p22 Mi2/ #v i?2 } M  
 L M/ i?2 `2; mH ` H BMB; m2 T22 b2 Mi2/ #v i?2 } M Bi2  
 i?2 M i?2 BM + i2M + iB'QM `2T`2 b2 Mi2/ b #2 HQRX



$$\begin{aligned}
 ([;]) = & \begin{matrix} \delta \\ \omega \\ \cdot \\ \omega \end{matrix} \begin{matrix} \mathcal{R}([;]) \\ \mathcal{R}([;]) \\ \mathcal{R}([;]) \\ \mathcal{K}([;]) \end{matrix} \begin{matrix} [2 Z_R^\wedge [626_R \\ [2 6_R^\wedge 6 \\ [2 6_R^\wedge = \\ [2 Z_k \end{matrix}
 \end{aligned}$$

\*  $QM + i2M iB'QM,$

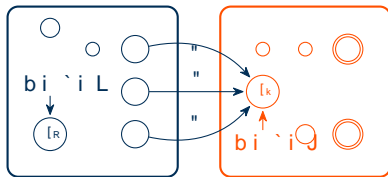
bbmK2 i? i i?2 `2; mH BH `M; m2 p22 Mi2/ #v i?2 }M  
 L M/ i?2 `2; mH ` H BMB; m2 T22 b2 Mi2/ #v i?2 }M Bi2  
 i?2 M i?2 BM + i2 M + i B'QM `2 T`2 b2 Mi2/ b #2 HQRX



$$\begin{pmatrix} [; ] \end{pmatrix} = \begin{matrix} \cdot W \\ \cdot W \end{matrix} \begin{pmatrix} R [; ] \\ R [; ] \\ R [; ] \\ R [; ] \end{pmatrix} \begin{matrix} [f \\ [k] \end{matrix} \begin{pmatrix} [2 Z_R^{\wedge} [626_R \\ [2 6_R^{\wedge} \Theta \\ [2 6_R^{\wedge} = \\ [2 Z_k \end{pmatrix}$$

\*  $QM + i^2 M i B' Q M,$

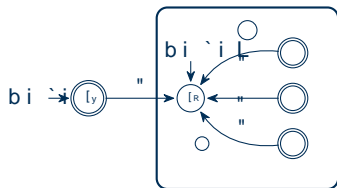
bbmK2 i? i i?2 `2; mH BH `M; m2 p22 Mi2/ #v i?2 } M  
 L M/ i?2 `2; mH ` H Bm; m2 T22 b2 Mi2/ #v i?2 } M B i2  
 i?2 M i?2 QM + i2 M + i B' Q M `2 T`2 b2 Mi2/ b #2 H Q r X



$$\begin{aligned}
 ([; ] ) = & \begin{matrix} \cdot W \\ \cdot W \end{matrix} \begin{matrix} \mathcal{R}([; ] ) \\ \mathcal{R}([; ] ) \\ \mathcal{R}([; ] ) [f [k] \\ \mathcal{K}([; ] ) \end{matrix} \begin{matrix} [2 Z_R^{\wedge} [626_R \\ [2 6_R^{\wedge} \mathcal{E} " \\ [2 6_R^{\wedge} = " \\ [2 Z_k \end{matrix}
 \end{aligned}$$

ai ` ,

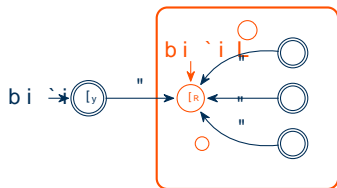
bbmK2 i? i i? 2 ` 2 ; m H B B ` M ; m 2 b 2 2 M i 2 / # v i ? 2 } M  
 L i ? 2 M i ? 2 r b M ` - v Q T 2 ` i Q ` T T H + B M / # Q ` 2 T ` 2 b 2 M i  
 # 2 H Q r X



$$\begin{aligned}
 ([; ] = & \begin{matrix} \text{8} \\ \text{WWW} \\ \text{WWW} \end{matrix} \begin{matrix} R([; ) \\ R([; ) \\ R([; ) \end{matrix} \begin{matrix} [2 ZR^{\wedge} 626R \\ [2 6R^{\wedge} 6 \\ [2 6R^{\wedge} = \\ [= [y^{\wedge} = \\ [= [y^{\wedge} 6 \end{matrix} \\
 & f [R] [f [R] \\
 & ;
 \end{aligned}$$

ai ` ,

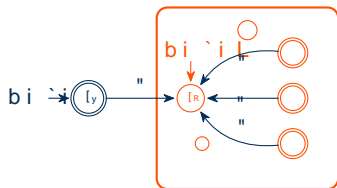
bbmK2 i? i i?2 `2 ;mH B B `M ;m2 b22 Mi2/ #v i?2 }M  
 L i?2M i?2 rbM`-vQT2` iQ` TTH+B M/ #Q `2T`2b2Mi  
 #2HQrX



$$\begin{aligned}
 ([;]) &= \begin{matrix} \text{8} \\ \text{WWW} \\ \text{WWW} \end{matrix} \begin{matrix} R([;]) \\ R([;]) \\ R([;]) \end{matrix} \begin{matrix} [2 Z_R^A & 626_R \\ [2 6_R^A & 6 \\ [2 6_R^A & = \\ [= [y^A & = \\ [= [y^A & 6 \end{matrix} \\
 & \begin{matrix} f[R] \\ ; \end{matrix} \begin{matrix} [f [R] \\ [R] \\ [R] \\ [y^A \\ [y^A \end{matrix}
 \end{aligned}$$

ai ` ,

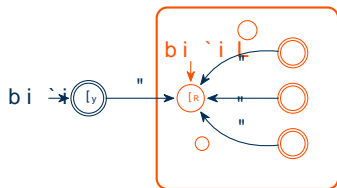
bbmK2 i? i i?2 `2 ;mH B B `M ;m2 b22 Mi2/ #v i?2 }M  
 L i?2M i?2 rbM`-vQT2` iQ` TTH+B M/ #Q `2T`2b2Mi  
 #2HQrX



$$\begin{aligned}
 ([; ] = & \begin{matrix} \text{8} \\ \text{WWW} \\ \text{WWW} \end{matrix} \begin{matrix} R([; ) \\ R([; ) \\ R([; ) \end{matrix} \begin{matrix} [2 ZR^{\wedge} 626R \\ [2 6R^{\wedge} 6" \\ [2 6R^{\wedge} = " \\ [= [y^{\wedge} = " \\ [= [y^{\wedge} 6" \end{matrix} \\
 & f [R] [R]
 \end{aligned}$$

ai ` ,

bbmK2 i? i i?2 `2 ;mH B B `M ;Tm2 b22 Mi2/ #v i?2 }M  
 L i?2M i?2 rbM`-vQT2` iQ` TTH+B M/ #Q `2T`2b2Mi  
 #2HQrX

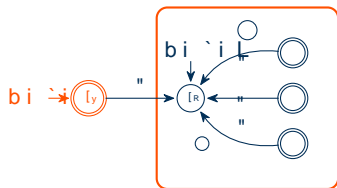


$$\begin{aligned}
 ([; ) = & \begin{matrix} \text{8} \\ \text{WWW} \\ \text{WWW} \end{matrix} \begin{matrix} R([; ) \\ R([; ) \\ R([; ) [f [R] \end{matrix} \begin{matrix} [2 ZR^{\wedge} 626R \\ [2 6R^{\wedge} 6 " \\ [2 6R^{\wedge} = " \\ [= [y^{\wedge} = " \\ [= [y^{\wedge} 6 " \end{matrix}
 \end{aligned}$$



ai ` ,

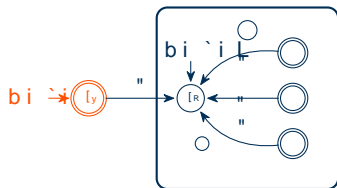
bbmK2 i? i i? 2 ` 2 ; m H B B ` M ; m 2 b 2 2 M i 2 / # v i ? 2 } M  
 L i ? 2 M i ? 2 r b M ` - v Q T 2 ` i Q ` T T H + B M / # Q ` 2 T ` 2 b 2 M i  
 # 2 H Q r X



$$\begin{aligned}
 ([; ) = & \begin{matrix} \text{8} \\ \text{WWW} \\ \text{WWW} \end{matrix} \begin{matrix} R([; ) \\ R([; ) \\ R([; ) \end{matrix} \begin{matrix} [2 Z_R^{\wedge} 626_R \\ [2 6_R^{\wedge} 6 \\ [2 6_R^{\wedge} = \\ [= [y^{\wedge} = \\ [= [y^{\wedge} 6 \end{matrix} \\
 & \begin{matrix} f [R \\ ; \end{matrix} \begin{matrix} [f [R \\ \\ \\ \\ \end{matrix}
 \end{aligned}$$

ai ` ,

bbmK2 i? i i? 2 ` 2 ; m H B B ` M ; m 2 b 2 2 M i 2 / # v i ? 2 } M  
 L i ? 2 M i ? 2 r b M ` - v Q T 2 ` i Q ` T T H + B M / # Q ` 2 T ` 2 b 2 M i  
 # 2 H Q r X



$$\begin{aligned}
 ([; ) = & \begin{matrix} \text{8} \\ \text{WWW} \\ \text{WWW} \end{matrix} \begin{matrix} R ([; ) \\ R ([; ) \\ R ([; ) \end{matrix} \begin{matrix} [2 Z_R^{\wedge} 626_R \\ [2 6_R^{\wedge} 6 " \\ [2 6_R^{\wedge} = " \\ [= [y^{\wedge} = " \\ [= [y^{\wedge} 6 " \end{matrix} \\
 & f [R]
 \end{aligned}$$

# h #H2 Q7 \*QM i2Mib

R 6BMBi2 miQK i

k L2r 6`QK PH/

j LQM@.2i2`KBMBbiB+ pbX .2i2`KBMBbiB+

g L2r 6`QK PH/ U ; BMV

8 L2ti \*H bb

# L2ti \*H bb

\_2;mH ` 1tT`2bbBQMb

L2ti \*H bb

\_2;mH ` 1tT`2bbBQMb

:2M2` HBx2/ LQM/2i2`KBMBbiB+ 6BMBi2 mi

## L2ti \*H bb

\_2;mH ` 1tT`2bbBQMb

:2M2` HBx2/ LQM/2i2`KBMBbiB+ 6BMBi2 mi

SmKTBM; G2KK

# Next Class

- Regular Expressions
- Generalized Nondeterministic Finite Automata
- Pumping Lemma
- Nonregular Languages



# Introduction to Finite Automata

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