

Lectures on Multivariable Mathematics: Inner Products, Norms, and Orthogonalization

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- 3 Linear Regression
- 4 Inner Products and Norms
- 5 Regression Revisited

Objectives

After this lesson you should be able to:

- 1 Define inner products,

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- 2 Understand the relation of inner products to norms,

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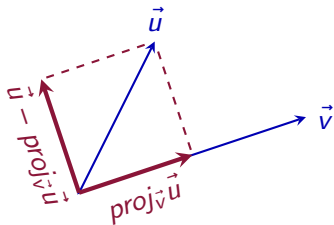
- 1 Define inner products,
- 2 Understand the relation of inner products to norms,
- 3 Recognize inner products beyond matrices and vectors,
- 4 Construct and utilize orthonormal bases,
- 5 Find the QR-Decomposition of a matrix, and
- 6 Use orthogonalization and projections to fit data to a curve.

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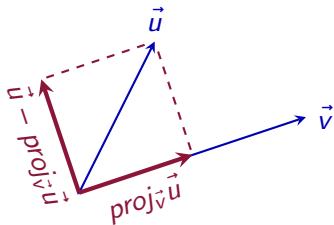
Recall Vector Projections

$$\text{proj}_{\vec{v}} \vec{u} = \frac{\vec{u} \cdot \vec{v}}{\vec{v} \cdot \vec{v}} \vec{v} = \left(\frac{\|\vec{u}\| \|\vec{v}\| \cos(\theta)}{\|\vec{v}\|^2} \right) \left(\frac{\vec{v}}{\|\vec{v}\|} \right)$$



Recall Vector Projections

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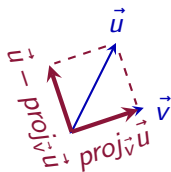
Note that we divide the \vec{v} by its own length to create a vector of length one, this is called **normalizing**.

Orthogonal and Orthonormal Vectors

Definition (Normalizing and Normal Vectors)

Given a vector \vec{v} we say that $\vec{v}/\|\vec{v}\|$ is the **normalized** version of \vec{v} and is called a **normal vector**.

$$\text{proj}_{\vec{v}}\vec{u} = \frac{\vec{u} \cdot \vec{v}}{\vec{v} \cdot \vec{v}} \vec{v} = \cos(\theta) \vec{v}$$



Orthogonal Matrices

In this product, $A^T A$, the columns of A are orthogonal so we get a diagonal matrix.

$$\begin{pmatrix} 1 & -3 & 0 \\ 3 & 1 & 1 \\ -3 & -1 & 10 \end{pmatrix} \begin{pmatrix} 1 & 3 & -3 \\ -3 & 1 & -1 \\ 0 & 1 & 10 \end{pmatrix} = \begin{pmatrix} 10 & 0 & 0 \\ 0 & 11 & 0 \\ 0 & 0 & 110 \end{pmatrix}$$

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$$\begin{pmatrix} \frac{1}{\sqrt{10}} & -\frac{3}{\sqrt{10}} & 0 \\ \frac{3}{\sqrt{11}} & \frac{1}{\sqrt{11}} & \frac{1}{\sqrt{11}} \\ -\frac{3}{\sqrt{110}} & -\frac{1}{\sqrt{110}} & \frac{10}{\sqrt{110}} \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{10}} & \frac{3}{\sqrt{11}} & -\frac{3}{\sqrt{110}} \\ -\frac{3}{\sqrt{10}} & \frac{1}{\sqrt{11}} & -\frac{1}{\sqrt{110}} \\ 0 & \frac{1}{\sqrt{11}} & \frac{10}{\sqrt{110}} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

If we normalize the columns, then A and A^T are inverses. These are **orthogonal matrices**.

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If we normalize the columns, then A and A^T are inverses. These are **orthogonal matrices**.

Orthogonal and Orthonormal Basis

Definition

A basis for a vector space is an **orthogonal basis** if all the vectors in the basis are mutually perpendicular. If, in addition, the vectors have unit length, then we say the basis is **orthonormal**.

$$B = \left\{ \begin{pmatrix} 1 \\ -3 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} -3 \\ -1 \\ 10 \end{pmatrix} \right\}$$

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A basis for a vector space is an **orthogonal basis** if all the vectors in the basis are mutually perpendicular. If, in addition, the vectors have unit length, then we say the basis is **orthonormal**.

Definition

A matrix whose columns form an orthonormal basis is called an **orthogonal matrix**.

$$A = \begin{pmatrix} \frac{1}{\sqrt{10}} & \frac{3}{\sqrt{11}} & -\frac{3}{\sqrt{110}} \\ -\frac{3}{\sqrt{10}} & \frac{1}{\sqrt{11}} & -\frac{1}{\sqrt{110}} \\ 0 & \frac{1}{\sqrt{11}} & \frac{10}{\sqrt{110}} \end{pmatrix}$$

Orthogonal Complements

Definition

Given a set of vectors W in \mathbb{R}^n , the **orthogonal complement** of W , written W^\perp , is the set of all vectors in \mathbb{R}^n perpendicular to the vectors in W .

$$W = \left\{ \begin{pmatrix} 1 \\ -3 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix} \right\}$$

$$W^\perp = \left\{ \begin{pmatrix} -3 \\ -1 \\ 10 \end{pmatrix} \right\}$$

Orthogonal Decomposition Theorem (Statement & Example)

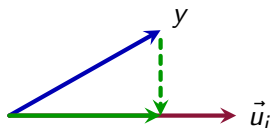
Theorem (Orthogonal Decomposition Theorem)

Let W be a subspace of \mathbb{R}^n , then each $y \in \mathbb{R}^n$ can be written uniquely in the form $y = \hat{y} + z$ where $\hat{y} \in W$ and $z \in W^\perp$. In fact, if $\{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_k\}$ is an orthogonal basis for W , then

$$\hat{y} = \frac{y \cdot \vec{u}_1}{\vec{u}_1 \cdot \vec{u}_1} \vec{u}_1 + \dots + \frac{y \cdot \vec{u}_k}{\vec{u}_k \cdot \vec{u}_k} \vec{u}_k, = \sum_{\vec{u}_i} \text{proj}_{\vec{u}_i} y$$

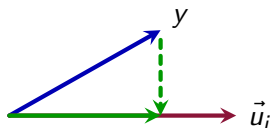
and $z = y - \hat{y}$.

Orthogonal Decomposition Theorem (Proof)



$$\text{proj}_{\vec{u}_i} y = \frac{y \cdot \vec{u}_i}{\vec{u}_i \cdot \vec{u}_i} \vec{u}_i$$

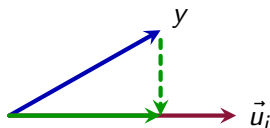
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$$\text{proj}_{\vec{u}_i} y = \frac{y \cdot \vec{u}_i}{\vec{u}_i \cdot \vec{u}_i} \vec{u}_i$$

$$z \cdot \vec{u}_i = (y - \hat{y}) \cdot \vec{u}_i$$

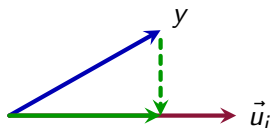
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$$\begin{aligned} z \cdot \vec{u}_i &= (y - \hat{y}) \cdot \vec{u}_i \\ &= y \cdot \vec{u}_i - \hat{y} \cdot \vec{u}_i \end{aligned}$$

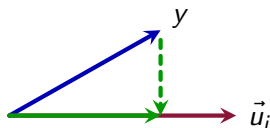
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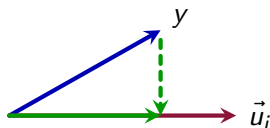
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Orthogonal Decomposition Theorem (Proof)



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Gram-Schmidt Process (with Normalization)

Given a basis for a vector space we can create an orthonormal basis using the **Gram-Schmidt Process** as follows:

- 1 Select one vector \vec{u} from the Basis
- 2 Normalize \vec{u} and add it to a New Basis
- 3 For each of the remaining vectors y in the basis
 - 1 Project it onto each vector \vec{u}_i in the New Basis, $proj_{\vec{u}_i} y$
 - 2 Sum those projections, $\hat{y} = \sum_{\vec{u}_i} proj_{\vec{u}_i} y$
 - 3 Subtract the sum from given vector, $z = y - \hat{y}$
 - 4 Normalize this new vector, $z = z / \|z\|$
 - 5 Add the new vector to the New Basis

Gram-Schmidt Process (with Normalization)

Here we start with

$$B = \{\langle 1, 1, 0 \rangle, \langle 2, 0, 1 \rangle, \langle 1, 1, 1 \rangle\}$$

and step through the Gram-Schmidt Process.

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$$\hat{B} = \{\langle 1/\sqrt{2}, 1/\sqrt{2}, 0 \rangle, \langle 1/\sqrt{3}, -1/\sqrt{3}, 1/\sqrt{3} \rangle, \langle -1/\sqrt{6}, 1/\sqrt{6}, 2/\sqrt{6} \rangle\}$$

Couple Important Points

Theorem (Best Approximation)

With W , y , and \hat{y} as in the Orthogonal Decomposition Theorem (theorem 5), for any vector $\vec{w} \in W$,

$$\|y - \hat{y}\| \leq \|y - \vec{w}\|.$$

in this sense \hat{y} is the nearest point to, and best approximation of, y in W .

Theorem (Orthogonal Matrices and Projections)

With W and y as in the Orthogonal Decomposition Theorem (theorem 5), if the columns of the matrix $U = [\vec{u}_1 \vec{u}_2 \cdots \vec{u}_k]$ are an orthonormal basis for W , then

$$\hat{y} = \text{proj}_W y = UU^T y.$$

QR-Decomposition: Example

Begin with A which has linearly independent columns. Apply Gram-Schmidt (with normalization) to the columns to get Q , then let $R = Q^T A$.

$$A = \begin{pmatrix} 1 & 2 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} \quad Q = \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{3} \\ 1/\sqrt{2} & -1/\sqrt{3} \\ 0 & 1/\sqrt{3} \end{pmatrix} \quad R = Q^T A = \begin{pmatrix} \sqrt{2} & 3/\sqrt{2} \\ 0 & \sqrt{3} \end{pmatrix}$$

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$$QR = Q(Q^T A) = (QQ^T)A = IA = A$$

QR-Decomposition: Definition

Theorem (QR Factorization)

If A is an $m \times n$ matrix with linearly independent columns and Q is an $m \times n$ matrix whose columns are an orthonormal basis for the column space of A , then there exists R an $n \times n$ upper triangular matrix with positive entries on the diagonal, specifically $R = Q^T A$.

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Find the equation of the line $y = mx + b$ passing through $P = (1, 2)$ and $Q = (-3, 7)$.

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$$\begin{pmatrix} 1 & 1 \\ -3 & 1 \end{pmatrix} \begin{pmatrix} m \\ b \end{pmatrix} = \begin{pmatrix} m + b \\ -3m + b \end{pmatrix} = \begin{pmatrix} 2 \\ 7 \end{pmatrix}$$

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$$\begin{pmatrix} m \\ b \end{pmatrix} = \begin{pmatrix} -5/4 \\ 13/4 \end{pmatrix}$$

Fitting Curves to Data (Quadratic)

Find the quadratic $y = ax^2 + bx + c$ passing through (1,9), (2,15), and (-3,5).

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Find the quadratic $y = ax^2 + bx + c$ passing through (1,9), (2,15), and (-3,5).

$$\begin{pmatrix} 1 & 1 & 1 \\ 4 & 2 & 1 \\ 9 & -3 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 9 \\ 15 \\ 5 \end{pmatrix}$$

$$\begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} -1/4 & 1/5 & 1/20 \\ -1/4 & 2/5 & -3/20 \\ 3/2 & -3/5 & 1/10 \end{pmatrix} \begin{pmatrix} 9 \\ 15 \\ 5 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \\ 5 \end{pmatrix}$$

Fitting Curves to Data (“Too Much” Data)

Find a line passing through $(1,9)$, $(2,15)$, and $(-3,5)$.

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$$\begin{pmatrix} 1 & 1 \\ 2 & 1 \\ -3 & 1 \end{pmatrix} \begin{pmatrix} m \\ b \end{pmatrix} = \begin{pmatrix} 9 \\ 15 \\ 5 \end{pmatrix}$$

?

Least-Squares: Definition

Definition (Least-Squares Solution)

If A is an $m \times n$ matrix and \vec{b} is in \mathbb{R}^m , a **least-squares solution** of $A\vec{x} = \vec{b}$ is an $\hat{x} \in \mathbb{R}^n$ such that

$$\|\vec{b} - A\hat{x}\| \leq \|\vec{b} - A\vec{x}\|$$

for all $\vec{x} \in \mathbb{R}^n$.

(Compare to the Best Approximation Theorem (thm. 6))

Least-Squares: Construction Theorem

Theorem

Let A be an $m \times n$ matrix. The following are equivalent:

- 1 The equation $A\vec{x} = \vec{b}$ has a unique least squares solution for each \vec{b} .
- 2 The columns of A are linearly independent.
- 3 The matrix $A^T A$ is invertible.

(Compare to Orthogonal Matrices and Projections theorem (thm. 5))

If these statements are true then we can write $A = QR$ (thm. 8) and then

$$\hat{x} = (A^T A)^{-1} A^T b = R^{-1} Q^T b$$

is the least-squares solution.

Least-Squares: Example

Find a line passing through (1,9), (2,15), and (-3,5).

$$\begin{pmatrix} 1 & 1 \\ 2 & 1 \\ -3 & 1 \end{pmatrix} \begin{pmatrix} m \\ b \end{pmatrix} = \begin{pmatrix} 9 \\ 15 \\ 5 \end{pmatrix}$$

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$$\begin{pmatrix} 1 & 2 & -3 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 2 & 1 \\ -3 & 1 \end{pmatrix} \begin{pmatrix} m \\ b \end{pmatrix} = \begin{pmatrix} 1 & 2 & -3 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 9 \\ 15 \\ 5 \end{pmatrix}$$
$$\begin{pmatrix} 14 & 0 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} m \\ b \end{pmatrix} = \begin{pmatrix} 24 \\ 29 \end{pmatrix}$$

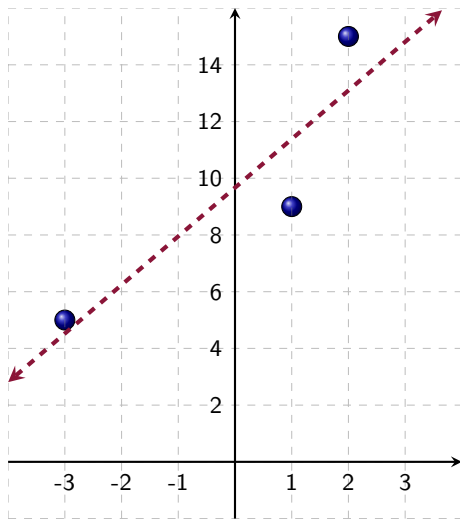
Least-Squares: Example

Find a line passing through (1,9), (2,15), and (-3,5).

$$\begin{pmatrix} 14 & 0 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} m \\ b \end{pmatrix} = \begin{pmatrix} 24 \\ 29 \end{pmatrix}$$
$$\begin{pmatrix} m \\ b \end{pmatrix} = \begin{pmatrix} 24/14 \\ 29/3 \end{pmatrix}$$

Least-Squares: Example

Find a line passing through $(1,9)$, $(2,15)$, and $(-3,5)$.



Multiple Regression

Given a data set with nutritional data on 77 different cereals¹, we can fit a plane to the following linear model:

$$\text{calories/cup} = a (\text{fiber/cup}) + b (\text{fat/cup}) + c$$

by creating a matrix A whose first columns are the measures of the fiber and the fat and the third column is ones (for the constant term):

$$A = \begin{pmatrix} \text{fiber} & \text{fat} & 1 \end{pmatrix}.$$

Then multiplying $(A^T A)^{-1} A^T$ by the vector of calories we get $a \approx 3.08$, $b \approx 18.67$, and $c = 105.45$, i.e.

$$\text{calories/cup} \approx 3.08 \text{ fiber/cup} + 18.67 \text{ fat/cup} + 105.45.$$

¹(https://domo-support.domo.com/s/article/360043931814?language=en_US)

Multiple Regression (Code)

```
# Input
import numpy as np
from numpy import linalg as la
import pandas as pd
df = pd.read_csv('cereal.csv')
cal = np.array(df['calories'])
fiber = np.array(df['fiber'])
fat = np.array(df['fat'])
cups = np.array(df['cups'])
cnt, = cal.shape
A = np.column_stack([fiber/cups, fat/cups, np.ones(cnt)])
la.inv(A.transpose()@A)@A.transpose()@(cal/cups)
# Output
array([ 3.0792079 , 18.67123465, 105.45361462])
```

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Inner Product: The Dot Product Generalized

Definition (Inner Product)

An **inner product** on a vector space V is a binary function from V to \mathbb{R} such that

- 1 $\langle u, v \rangle = \langle v, u \rangle$
- 2 $\langle u + w, v \rangle = \langle u, v \rangle + \langle w, v \rangle$
- 3 $\langle cu, v \rangle = \langle u, cv \rangle = c\langle u, v \rangle$
- 4 $\langle u, u \rangle \geq 0$ with equality only when $u = 0$

A vector space with an inner product is called an **inner product space**.

The Norm Generalized

Definition (Norm)

In an inner product space we can define the **norm** of a vector as

$$\|u\| = \sqrt{\langle u, u \rangle}.$$

Then distance and orthogonality are measured as before.

Weighted Inner Product in \mathbb{R}^3

Here is an inner product that weights the x -coordinate twice the y and the y -coordinate twice the z

$$\langle u, v \rangle = u^t A v = \begin{pmatrix} x_0 & y_0 & z_0 \end{pmatrix} \begin{pmatrix} 4 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} = 4x_0x_1 + 2y_0y_1 + z_0z_1.$$

Since the matrix in the middle is **symmetric**, $A = A^T$, this will satisfy the definition of an inner product.

Inner Product for \mathbb{P}_2

Given two polynomials in \mathbb{P}_2 (quadratic and below) define

$$\langle p, q \rangle = p(-1)q(-1) + p(0)q(0) + p(1)q(1).$$

Since quadratics are uniquely determined by three points, this will define an inner product on \mathbb{P}_2 . Therefore we can make sense of norms, projections, and orthogonalization for polynomials.

Inner Product for \mathbb{P}_2

We can project $p(t) = 7 - t^4$ onto \mathbb{P}_2 with basis

$$p_0 = 1, \quad p_1 = t, \quad p_2 = t^2 - 2/3$$

using the previous inner product:

$$\begin{aligned} \text{proj}_{\mathbb{P}_2} p(t) &= \frac{\langle p_0, p \rangle}{\langle p_0, p_0 \rangle} p_0 + \frac{\langle p_1, p \rangle}{\langle p_1, p_1 \rangle} p_1 + \frac{\langle p_2, p \rangle}{\langle p_2, p_2 \rangle} p_2 \\ &= \frac{19}{3} + \frac{0}{2}t - (t^2 - 2/3) \\ &= 7 - t^2. \end{aligned}$$

So the best quadratic approximation of $p(t) = 7 - t^4$ is $7 - t^2$

Inner Product with Continuous Functions

Given functions $f(x)$ and $g(x)$ continuous on $[a, b]$, i.e. $f, g \in C[a, b]$, we can define:

$$\langle f, g \rangle = \int_a^b f(x)g(x) dx.$$

In particular $p_0(t) = 1$ and $p_1(t) = t$ are orthogonal in $C[-1, 1]$:

$$\langle 1, t \rangle = \int_{-1}^1 t dx = 0.$$

And if we apply the Orthogonal Decomposition Theorem (thm. 5) to $p_2(t) = t^2$ we get:

$$z_2(t) = t^2 - \frac{\int_{-1}^1 1 \cdot t^2 dt}{\int_{-1}^1 1 \cdot 1 dt} + \frac{\int_{-1}^1 t \cdot t^2 dt}{\int_{-1}^1 t \cdot t dt} t = t^2 - 1/3$$

which is orthogonal to the other two functions.

Cauchy-Schwarz Inequality

Theorem (Cauchy-Schwarz Inequality)

Given an inner product space V ,

$$|\langle u, v \rangle| \leq \|u\| \|v\|.$$

Cauchy-Schwarz Inequality

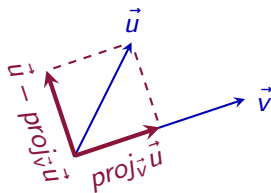
Theorem (Cauchy-Schwarz Inequality)

Given an inner product space V ,

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$$\|proj_v u\| = \frac{|\langle u, v \rangle|}{\|v\|^2} \|v\| = \frac{|\langle u, v \rangle|}{\|v\|}$$

$$proj_v \vec{u} = \frac{\vec{u} \cdot \vec{v}}{\vec{v} \cdot \vec{v}} \vec{v}$$



Cauchy-Schwarz Inequality

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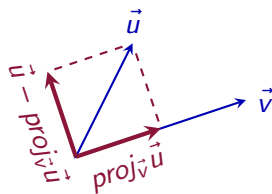
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Cauchy-Schwarz Inequality

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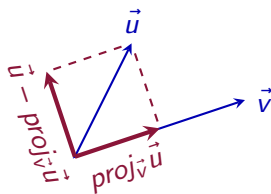
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$$\|proj_v u\| = \frac{|\langle u, v \rangle|}{\|v\|^2} \|v\| = \frac{|\langle u, v \rangle|}{\|v\|}$$

$$\begin{aligned} |\langle u, v \rangle| &= \|proj_v u\| \|v\| \\ &\leq \|u\| \|v\| \end{aligned}$$

$$proj_v \vec{u} = \frac{\vec{u} \cdot \vec{v}}{\vec{v} \cdot \vec{v}} \vec{v}$$



Triangle Inequality

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Triangle Inequality

Theorem (Triangle Inequality)

Given an inner product space V ,

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- 1 Objectives
- 2 Orthogonal Bases and Complements
- 3 Linear Regression
- 4 Inner Products and Norms
- 5 Regression Revisited**

Linear Regression: Trend Analysis (Introduction)

Definition (Trend Analysis)

Given a basis of orthogonal polynomials $\{p_0, p_1, \dots, p_k\}$ such that $\deg(p_i) = i$ and a collection of data points

$$\{(x_0, y_0), (x_1, y_1), \dots, (x_r, y_r)\},$$

which we think of as points on the graph of some function g of degree r , the projection of g onto the basis

$$\hat{g} = c_0 p_0 + c_1 p_1 + \dots + c_k p_k$$

is called the **trend function** and the c_i are the **trend coefficients**. Note that for each i , $c_i = \langle g, p_i \rangle / \langle p_i, p_i \rangle$ and is independent of the other c_j for $i \neq j$.

Linear Regression: Trend Analysis (Example)

Let our basis be:

$$B = \{p_0 = 1, p_1 = t, p_2 = t^2 - 2\}$$

and our data set be

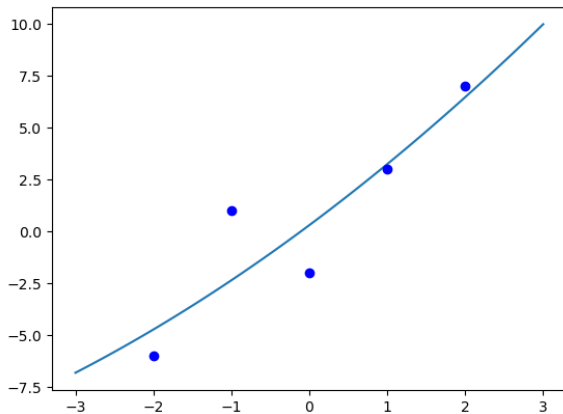
$$Data = \{(-2, -5), (-1, 1), (0, -2), (1, 3), (2, 7)\}.$$

Then the quadratic that fits this data to this basis is:

$$\hat{g} = \sum_{i=0}^2 \frac{\langle g, p_i \rangle}{\langle p_i, p_i \rangle} p_i \approx 0.14(t^2 - 2) + 2.8t + 0.6.$$

From this we can conclude that the linear trend is more than four times the quadratic trend, so the data seems primarily linear.

Linear Regression: Trend Analysis (Example)



Fourier Analysis (Introduction)

Definition (Fourier Approximations)

A function $f(x) \in C([0, 2\pi])$ can be approximated as closely as we like by

$$\frac{a_0}{2} + a_1 \cos(t) + b_1 \sin(t) + a_2 \cos(2t) + b_2 \sin(2t) + \cdots + a_n \cos(nt) + b_n \sin(nt)$$

for sufficiently large n . This is called a **trigonometric polynomial** or the n^{th} -order Fourier approximation.

Fourier Analysis (A Little Calculus)

If we define an inner product on $C[0, 2\pi]$ by $\int_0^{2\pi} f(t)g(t) dt$, similar to before, then the identities

$$2 \cos(ax) \cos(bx) = \cos(ax + bx) + \cos(ax - bx),$$

$$2 \cos(ax) \sin(bx) = \sin(ax + bx) + \sin(ax - bx), \text{ and}$$

$$2 \sin(ax) \sin(bx) = \cos(ax + bx) - \cos(ax - bx),$$

can be used to show the set

$$\{1, \cos(t), \sin(t), \cos(2t), \sin(2t), \dots, \cos(nt), \sin(nt)\}$$

form an orthogonal basis. Therefore we can find the coefficients for our Fourier approximation using projections:

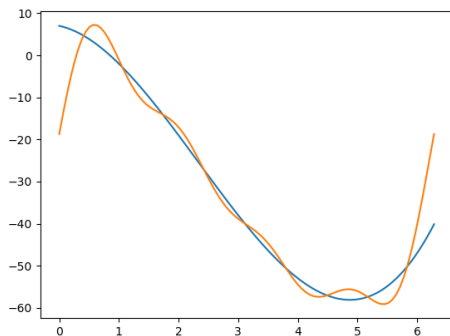
$$a_k = \frac{\langle f, \cos(kt) \rangle}{\langle \cos(kt), \cos(kt) \rangle} \text{ and } b_k = \frac{\langle f, \sin(kt) \rangle}{\langle \sin(kt), \sin(kt) \rangle}$$

for $k \geq 1$ and $a_0 = \langle f, 1 \rangle / \langle 1, 1 \rangle$.

Fourier Analysis (Example)

We can approximate the function $f(t) = t^3 - 7t^2 - 3t + 7$ using this approach and we get:

$$\begin{aligned}
 & -32.59 + 27.01 \sin(t) + 9.00 \sin(2t) + 5.45 \sin(3t) + 3.94 \sin(4t) \\
 & + 9.70 \cos(t) + 2.42 \cos(2t) + 1.08 \cos(3t) + 0.61 \cos(4t)
 \end{aligned}$$



Fourier Analysis Again (Another Example)

For a data set $\{(x_1, y_1), \dots, (x_n, y_n)\}$, we can redefine how we find the Fourier coefficients by using sums for the inner products, such as

$$\sum_{i=1}^n f(x_i) \cos\left(\frac{2k\pi}{\max_j(x_j)} x_i\right) \text{ and } \sum_{i=1}^n f(x_i) \sin\left(\frac{2k\pi}{\max_j(x_j)} x_i\right)$$

for the numerators in the projections. And for the denominators we use

$$\sum_{i=1}^n \cos\left(\frac{2k\pi}{\max_j(x_j)} x_i\right) \cos\left(\frac{2k\pi}{\max_j(x_j)} x_i\right)$$

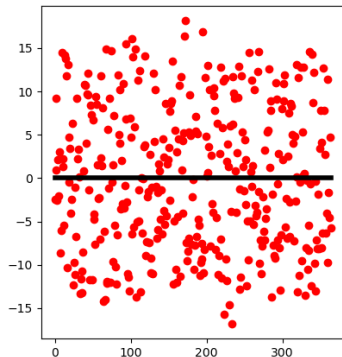
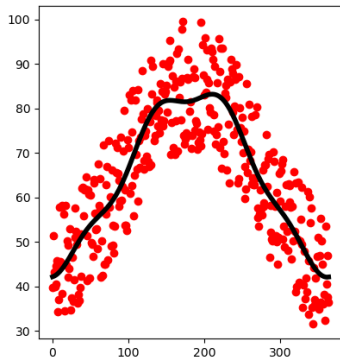
and

$$\sum_{i=1}^n \sin\left(\frac{2k\pi}{\max_j(x_j)} x_i\right) \sin\left(\frac{2k\pi}{\max_j(x_j)} x_i\right).$$

(Note this is a very primitive approach; a proper course specifically on data analysis would offer more detail.)

Fourier Analysis Again (Another Example)

If we have average daily temperature data throughout the year we can fit a curve to it:



Lectures on Multivariable Mathematics: Inner Products, Norms, and Orthogonalization

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